Partially fluidized shear granular flows: Continuum theory and molecular dynamics simulations

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The continuum theory of partially fluidized shear granular flows is tested and calibrated using two-dimensional soft particle molecular dynamics simulations. The theory is based on the relaxational dynamics of the order parameter that describes the transition between static and flowing regimes of granular material. We define the order parameter as a fraction of static contacts among all contacts between particles. We also propose and verify by direct simulations the constitutive relation based on the splitting of the shear stress tensor into a “fluid part” proportional to the strain rate tensor, and a remaining “solid part.” The ratio of these two parts is a function of the order parameter. The rheology of the fluid component agrees well with the kinetic theory of granular fluids even in the dense regime. Based on the hysteretic bifurcation diagram for a thin shear granular layer obtained in simulations, we construct the “free energy” for the order parameter. The theory calibrated using numerical experiments with the thin granular layer is applied to the surface-driven stationary two-dimensional granular flows in a thick granular layer under gravity.

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I. INTRODUCTION

In the last few years there have been many experimental [1–7] and theoretical [8–14] studies that explored a broad range of granular flow conditions from rapid dilute flows to slow dense flows, as well as the details of the shear-driven fluidization transition. While dilute granular flows can be well described by the kinetic theory of dissipative granular gases [15], dense granular flows still present significant difficulty in formulation of a continuous theory. In Ref. [16], Savage proposed a continuum theory for slow dense granular flows based on the so-called associated flow rule that relates the strain rate and the shear stress in plastic frictional systems. Averaging strain rate fluctuations yields a Bingham-like constitutive relation in which the shear stress has viscous as well as strain-rate independent parts. According to this theory, the stress and strain rate tensors are always coaxial and, furthermore, it also postulates that the viscosity diverges as the density approaches close packing limit. Losert et al. [3] (see also Ref. [17]) proposed a similar hydrodynamic model based on a Newtonian stress-strain constitutive relation with density dependent viscosity without strain-rate independent component. As observed in Ref. [3], the ratio of the full shear stress to the strain rate diverges at the fluidization threshold. This was also interpreted in Ref. [3] as a divergence of the viscosity coefficient when the volume fraction approaches the randomly packed limit. This description works only in a fluidized state and cannot properly account for hysteretic phenomena in which static and fluidized states coexist under the same external load such as stick-slip oscillations [2], avalanching [6], or shear band formation.

In many granular flows of interest static and dynamic regions coexist under the same external load conditions. Examples of such hysteretic phenomena include stick-slip oscillations [2], avalanching [6], or shear band formation. This calls for a unified theory which would be applicable both in the flowing regime and in the static regime.

In our recent papers [18,19] we proposed a different approach based on the order parameter description of the granular matter. The value of the order parameter specifies the ratio between static and fluid parts of the stress tensor. The order parameter was assumed to obey dissipative dynamics governed by a free energy functional with two local minima. This description based on the separation of static and fluid components of the shear stress, calls for an alternative definition of viscosity as a ratio of the fluid part of the shear stress to the strain rate. Since the fluid shear stress vanishes together with the strain rate, the viscosity coefficient in our theory is expected to remain finite at the fluidization threshold. We assumed the simplest Newtonian friction law, so the viscosity coefficient is a constant. This model yielded a good qualitative description of many phenomena occurring in granular flows, such as hysteretic transition to chute flow, stick-slip regime of a driven near-surface flow, structure of avalanches in shallow chute flows, etc.

However, several important issues have not been addressed: mesoscopic definition of the order parameter, quantitative specification of the order parameter dynamics and the constitutive relation. In this paper we set out to perform two-dimensional (2D) molecular dynamics (MD) simulations, which should provide us with the way to achieve these goals. We classify all contacts as either “fluidlike” or “solidlike” and define the order parameter as a mesoscopic space-time average fraction of solidlike contacts. Using this order parameter we obtain the constitutive relation and the relaxational dynamics of the order parameter directly from simulations of granular flow in a thin Couette geometry at zero gravity. Preliminary account of our results is presented in Ref. [20].

The paper is organized as follows. Section II outlines the standard granular hydrodynamics theory based on the kinetic theory of dissipative granular gases. Sec. III introduces the continuum description of partially fluidized flows based on the relaxational dynamics of the order parameter. In Sec. IV we describe our 2D molecular dynamics simulations and define measurement protocol for the order parameter and fluid
and solid components of the stress tensor. In Sec. V we study the Couette flow in a thin granular layer to obtain the free energy controlling the relaxational order parameter dynamics and to extract the constitutive relations. In Sec. VI the obtained set of equations is used to calculate the stress and velocity distributions in a different system, a thick granular layer under nonzero gravity driven by a moving heavy upper plate.

II. GRANULAR HYDRODYNAMICS

In this section we outline the standard continuum description of granular flows based on continuity equations for mass, momentum, and fluctuation kinetic energy (or “granular temperature”). This description is usually applied to dilute granular gases where it can be rigorously derived from the kinetic theory [15], although slightly modified hydrodynamics based on kinetic theory often works reasonably well for relatively dense flows, even though the kinetic theory itself is not applicable to these conditions.

The mass, momentum, and energy conservation equations have the usual form

\[
\frac{D \rho}{D t} = -\nabla \cdot \mathbf{u},
\]

\[
\frac{D \mathbf{u}}{D t} = -\nabla \sigma + \rho \mathbf{g},
\]

\[
\frac{D T}{D t} = -\mathbf{\sigma} \cdot \dot{\gamma} - \nabla \cdot \mathbf{q} - \dot{\varepsilon},
\]

where \( \rho \) is the density, \( \mathbf{u} \) is the velocity field, \( T = (\mathbf{u}^2) - \langle \mathbf{u}^2 \rangle / 2 \) is the granular temperature, \( D/Dt = \partial_t + (\mathbf{u} \cdot \nabla) \) is the material derivative, \( \mathbf{g} \) is the gravity acceleration, \( \sigma_{ab} \) is the stress tensor, \( \mathbf{q} \) is the energy flux vector, \( \dot{\gamma} = \partial_a u_b + \partial_b u_a \) is the strain rate tensor, and \( \dot{\varepsilon} \) is the energy dissipation rate.

These three equations have to be supplemented by the constitutive relations for the stress tensor \( \sigma \), energy flux \( \mathbf{q} \), and the energy dissipation rate \( \dot{\varepsilon} \). For dilute systems, a linear relation between stress \( \sigma \) and strain rate \( \dot{\gamma} \) is obtained,

\[
\sigma_{ab} = \left[ p + (\mu - \lambda) \mathrm{Tr} \dot{\gamma} \right] \delta_{ab} - \mu \dot{\gamma}_{ab},
\]

\[
\mathbf{q} = -\kappa \nabla T.
\]

In the kinetic theory of granular gases [15], these equations are closed with the following equation of state

\[
p = \frac{4 \nu T}{\pi d^2} \left[ 1 + (1 + e) G(\nu) \right],
\]

and the expressions for the shear and bulk viscosities

\[
\mu = \frac{\nu T^{1/2}}{2 \pi^{1/2} d G(\nu)} \left[ 1 + 2 G(\nu) + \left( 1 + \frac{8}{\pi} \right) G(\nu)^2 \right].
\]

Here \( 0 < e < 1 \) is restitution coefficient and \( d \) is particle diameter. The function \( G(\nu) \) which enters these relations is the spatial particle-particle correlation function, and for a dilute 2D gas of elastic hard disks was derived by Carnahan and Starling [21],

\[
G_{CS}(\nu) = \frac{\nu(1-7 \nu/16)}{(1-\nu^2)^2}.
\]

This formula is expected to work for densities roughly below 0.7. For high density granular gases, this function has been calculated using free volume theory [22],

\[
G_{FV} = \frac{1}{1 + e \left[ (\nu_c / \nu)^{1/2} - 1 \right]},
\]

where \( \nu_c \approx 0.82 \) is the density of the random close packing limit. Luding [24] proposed a global fit

\[
G_L = G_{CS} + \left\{ 1 + \exp\left[ - (\nu - \nu_0)/m_0 \right] \right\}^{-1} (G_{FV} - G_{CS})
\]

with empirically fitted parameters \( \nu_0 \approx 0.7 \) and \( m_0 \approx 10^{-2} \). However, even with this extension, the continuum theory comprising of Eqs. (1)–(10) cannot describe the force chains that transmit stress via persistent contacts remaining in the dense granular flows, as well as the transition from solid to static regimes and coexisting solid and fluid phases.

III. ORDER PARAMETER DESCRIPTION OF PARTIALLY FLUIDIZED GRANULAR FLOWS

In this section we review briefly our continuum theory [18,19] that provides an alternative approach to the formulation of the constitutive relations in partially fluidized granular flows. In the dense flow regime, the granular matter can be considered incompressible, so Eq. (1) can be replaced by \( \nabla \cdot \mathbf{u} = 0 \) and the density \( \nu = \nu_c \). This also allows us to drop the energy equation (3) and the equation of state (6), as for \( \nu \rightarrow \nu_c , G(\nu) \rightarrow \infty \), and \( T \rightarrow 0 \), so that \( G(\nu) T \rightarrow \text{const} \). This, of course, leads to the familiar divergence of the viscosity coefficient \( \mu \propto G(\nu) T^{1/2} \).

Next, we separate the stress tensor \( \sigma \) into two parts, a static (contact) part \( \sigma^c \), and a fluid part \( \sigma^f \). The latter is assumed to take a purely Newtonian form.
where \( p_f \) is the “partial” fluid pressure, \( \mu_f \) is the viscosity coefficient associated with the fluid stress tensor, which is different from \( \mu \) introduced for the full stress tensor. As we shall see in the following, unlike \( \mu \), \( \mu_f \) does not diverge as \( \nu \to \nu_c \). In our original model \[18,19\] we simply assumed \( \mu_f = \text{const.} \)

We postulated \[25\] that the fluid part of the off-diagonal components of the stress tensor is proportional to the off-diagonal components of the full stress tensor with the proportionality coefficient being a function of the order parameter \( \rho \),

\[
\sigma_{xy}^f = q(\rho) \sigma_{xy}.
\]

This assumption stipulates the equation for the static part of the off-diagonal stress components,

\[
\sigma_{xy}^s = [1 - q(\rho)] \sigma_{xy}.
\]

Both fluid and solid parts of the stress tensor are assumed symmetric, \( \sigma_{xy}^s = \sigma_{yx}^s \). This assumption is confirmed by our numerical simulations (see below). We choose a fixed range for the order parameter such that it is 0 in a completely fluidized state and 1 in a completely static regime. Thus, the function \( q(\rho) \) has the property \( q(0) = 1 \), \( q(1) = 0 \). In Refs. \[18,19\] for simplicity we took \( q(\rho) = 1 - \rho \).

A similar relationship can be postulated for the diagonal terms of the stress tensor,

\[
\sigma_{xx}^f = q_x(\rho) \sigma_{xx}, \quad \sigma_{yy}^f = q_y(\rho) \sigma_{yy},
\]

\[
\sigma_{xx}^s = [1 - q_x(\rho)] \sigma_{xx}, \quad \sigma_{yy}^s = [1 - q_y(\rho)] \sigma_{yy},
\]

where the scaling functions \( q_x, q_y(\rho) \) can differ from \( q(\rho) \).

Combining Eqs. (14)–(18), we obtain the constitutive relation in the closed form,

\[
\sigma_{\alpha\beta}^s = p_f \delta_{\alpha\beta} / q(\rho) - \mu_f \gamma_{\alpha\beta} / q(\rho),
\]

where \( \alpha, \beta \in \{x, y\} \).

The order parameter itself was not related to any microscopic properties of granular assemblies in Refs. \[18,19\]. We simply assumed that because of strong dissipation in dense granular flows it has purely relaxational dynamics controlled by the Ginzburg-Landau equation,

\[
\frac{D\rho}{Dt} = D \nabla^2 \rho - \frac{\partial F(\rho)}{\partial \rho}.
\]

Here \( D \) is the diffusion coefficient and \( F(\rho) \) is the free energy density, which was assumed to have a quartic polynomial form to account for the bistability near the solid-fluid transition:

\[
F(\rho) = \int^\rho \rho (\rho - 1) (\rho - \delta) d\rho.
\]

The control parameter \( \delta \) is determined by the stress tensor, which in Ref. \[18,19\] was taken to be a linear function of \( \delta = \max[\sigma_{\mu\alpha}/\sigma_{\mu\mu} \] where the maximum is sought over all possible orthogonal directions \( \mu \) and \( \nu \). It is easy to see that in the interval \( 0 < \delta < 1 \), Eq. (20) has two stable uniform solutions \( \rho = 0.1 \) corresponding to fluid and solid states and one unstable solution \( \rho = \delta \).

Momentum conservation equation (2) together with Eqs. (19)–(21) represent a closed set of continuous equations, which, after being augmented by appropriate boundary conditions, can describe a variety of interesting granular flows such as avalanches in thin chute flows, drum flows, stick-slip oscillation in surface-driven flows, \[18,19\]. Since a rigorous derivation of the continuum model of dense partially fluidized flows from first principles does not seem feasible, the assumptions made ad hoc in the formulation of model (2) Eqs. (19)–(21) have to be checked against available experimental and/or numerical data. Unfortunately, it appears to be extremely difficult to directly measure the order parameter in the bulk of granular material, as it is determined by subtle changes in the contact fabric. In this paper we attempt to extract the properties of the order parameter from molecular dynamics simulations and on this basis make a quantitative fit of the order parameter model.

IV. MOLECULAR DYNAMICS SIMULATIONS

To model the interaction of individual grains we use the so-called soft-contact approach. The grains are assumed to be noncohesive, dry, inelastic disklike particles. Two grains interact via normal and shear forces whenever they overlap. For the normal impact we employ spring-dashpot model \[9\]. This model accounts for repulsion and dissipation: the repulsive component is proportional to the degree of the overlap, and the velocity dependent damping component simulates the dissipation. The model for shear force is based upon the technique developed by Cundall and Strack \[26\]. It incorporates tangential elasticity and Coulomb laws of friction. The elastic restoring force is proportional to the integrated tangential displacement during the contact and limited by the product of the friction coefficient and the instantaneous normal force. The grains possess two translational and one rotational degrees of freedom. The motion of a grain is obtained by integrating Newton’s equations with the forces and torques produced by its interactions with all the neighboring grains and walls of the container.

Consider a grain \( i \) of radius \( R_i \) located at \( \mathbf{r}_i \) moving with translational velocity \( \mathbf{v}_i \) and angular velocity \( \omega_i \). This grain is in contact with grain \( j \) whenever overlap \( \delta_{ij} = R_i + R_j > |\mathbf{r}_i - \mathbf{r}_j| > 0 \). The relative velocity at the contact point and its normal and tangent components are given by

\[
\mathbf{v}_{ij} = \mathbf{v}_i - \mathbf{v}_j + (R_i \omega_i + R_j \omega_j) \mathbf{n}_{ij},
\]

\[
\mathbf{v}_n = (\mathbf{v}_i - \mathbf{v}_j) \mathbf{n}_{ij}, \quad \mathbf{v}_t = (\mathbf{v}_i - \mathbf{v}_j) \mathbf{v}_{ij} + (R_i \omega_i + R_j \omega_j),
\]

where \( \mathbf{n}_{ij} = (\mathbf{r}_i - \mathbf{r}_j)/r_{ij} \) is the inward normal to the surface of \( i \) at the contact point with \( j \), and the direction of the tangent \( \mathbf{v}_{ij} = (n_y, -n_x) \) is colin-
ear with the angular velocity. Then the grain $i$ is subjected to the contact force due to the interaction with $j$ with normal and tangential components

$$F_n = k_n \delta_n - 2 \gamma_n m_i v_n,$$  \hspace{1cm} (24)

$$F_t = -\text{sign}(\delta_t) \min(|k_t|, |\mu_t F_n|), \quad \delta_t(t) = \int_{t_0}^{t} v_t(\tau) d\tau,$$  \hspace{1cm} (25)

where $k_{n,t}$ are the corresponding spring constants, $\gamma_n$ is the normal damping coefficient, $m_i = m_i' m_i/(m_i' + m_i')$ is the reduced mass, $\mu_t$ is coefficient of friction, and $\delta_t$ is tangential displacement since the moment $t_0$ of the initial contact between $i$ and $j$. When the steady yield criterion Eq. (25) is satisfied, the magnitude of $\delta_t$ is adjusted to an instantaneous equilibrium value providing $F_t = \mu_t F_n$. According to the analytical solution of the linear spring-dashpot model, the coefficient of restitution and the duration of heads-on collision are $e = \exp(-\gamma_t' \delta_t)$, $\tau_c = \pi/(k_n/m_e - \gamma_n^2)^{1/2}$.

The advantages and limitations of the employed contact force model were thoroughly studied by a number of authors [9,8,10]. In fact, this is the simplest model that allows us to account for both static and dynamic friction.

When all forces acting on grain $i$ from other grains, boundaries, and perhaps external fields are computed, the problem is reduced to the integration of Newton’s equations for translational and rotational degrees of freedom,

$$m_i \frac{d^2 \mathbf{r}_i}{dt^2} = m_i' \mathbf{g} + \sum_a F_a^{ic},$$

$$I_i \frac{d \mathbf{q}_i}{dt} = I_i' \sum_a F_a^{ic},$$  \hspace{1cm} (26)

where the mass of particle $i$ is denoted by $m_i'$ and its moment of inertia is $I_i' = 1/2 m_i' R_i^2$, $\mathbf{g}$ stands for an external gravity field, and the sums in Eqs. (26) and (27) run over all contacts of particle $i$.

The results of the simulations reported here are presented in dimensionless form. All quantities are normalized by an appropriate combination of the average particle diameter $d$, mass $m$, and gravity $g$.

Equations (26) and (27) were integrated using the fifth-order predictor-corrector [27] with a constant time step $\delta t$. The spring constant $k_n$ and damping coefficient $\gamma_n$ were chosen to provide the desired value of the restitution coefficient $e$ and guarantee an accurate resolution of an individual collision. Typically, we used $e = 0.92$, $\delta t = 10^{-4}$, $t_c = 50 \delta t$, $k_n = 2.0 \times 10^5$, $\gamma_n = 16.7$, $k_\alpha = 1/3 k_n$.

The computational domain spans $L_x \times L_y$ area, and is periodic in horizontal direction $x$. Unless otherwise mentioned, the granulate is slightly polydisperse to avoid crystallization effects [8]. We assume that the grain diameters are uniformly distributed around mean with relative width $\Delta_d$. To provide a link between micromechanical quantities obtained through simulations and continuous fields, we define the following coarse-graining procedure. Since all experiments described below deal with steady quantities, the procedure consists of two steps: space and then time averaging. The space averaging of a field $x$ is performed over horizontal bins (along the flow direction) of size $V_b = L_x \times 1$ and is denoted as $\langle x \rangle$ in the following. Contributions of those particles that only partially belong to a certain bin are weighted by the fraction of their area. After a simulation has reached a steady state, instantaneous profiles are averaged over a suitable number of time snapshots. We shall denote the time averaging with $\tilde{x}$.

For example, steady solid fraction profile is given by

$$\nu(y) = \langle \nu(y, t) \rangle,$$

$$\langle \nu(y, t) \rangle = V_b^{-1} \sum_{i \in V_b} w_i(y) V_i,$$  \hspace{1cm} (28)

where the summation runs over grains at least partially in a bin $V_b$ centered at $y$, $V_i$ is the area of grain $i$, and $w_i(y)$ is a corresponding fraction of a grain’s area within $V_b$. The coarse-grained velocity field is

$$\mathbf{u}(y) = \langle \mathbf{u}(y, t) \rangle,$$

$$\langle \mathbf{u}(y, t) \rangle = \nu(y, t)^{-1} \langle \mathbf{v}(y, t) \rangle$$

$$= \nu(y, t)^{-1} V_b^{-1} \sum_{i \in V_b} w_i(y) V_i \mathbf{v}_i.$$  \hspace{1cm} (29)

For simplicity, we extend the space-time averaging technique described above for other quantities, such as the stress tensor

$$\sigma_{\alpha\beta}(y) = \langle \sigma_{\alpha\beta}(y, t) \rangle,$$

$$\langle \sigma_{\alpha\beta}(y, t) \rangle = \left\langle \frac{1}{2} \sum_{ic} r_i^{ic} F_{ic}^{ic} \right\rangle + \left\langle m_i v_i^{ic} \tilde{v}_i^{ic} \right\rangle.$$  \hspace{1cm} (30)

where $\alpha, \beta = \{x,y\}$, $r_i^{ic} = r_i^{ic} \cdot e_a$, $F_{ic}^{ic} = F_{ic} \cdot e_a$, $v_i^{ic} = v_i^{ic} - \langle v_i^{ic} \rangle$.

The stress tensor in Eq. (30) has two distinct components. The first one—virial or contact—describes pairwise interactions of grains. The second one—kinetic or Reynolds—is due to velocity fluctuations.

A. Order parameter for granular fluidization: Static contacts vs fluid contacts

At any moment of time all contacts are classified as either “fluid” or “solid.” A contact is considered “solid” if it is in a stuck state ($F_t < \mu_t F_n$) and its duration is longer than a typical time of collision $t_c$. The first requirement eliminates long-lasting sliding contacts, and the second requirement excludes short-term collisions pertinent for completely fluidized regimes. We choose a typical collision to last $t^* = 1.1 t_c$. When either of the requirements is not fulfilled, the contact is assumed “fluid.”

We define the order parameter as the ratio between space-time averaged numbers of “solid” contacts $\langle Z_s \rangle$ and all contacts $\langle Z \rangle$ within a sampling area [23],

$$\rho(y) = \langle Z_s \rangle / \langle Z \rangle.$$  \hspace{1cm} (31)
This definition endures at least two limiting cases: when granulate is in a static state and when it is strongly agitated, i.e., completely fluidized. In fact, in the former quiescent state all contacts are stuck and $\rho = 1$. In the fluidized case $\langle Z_s \rangle$ is 0 and $\langle Z \rangle$ is small but finite, therefore $\rho = 0$.

Let us note that the order parameter $\rho$ just introduced is expected to be as sensitive to the degree of fluidization as the stress tensor. A small rearrangement of the force network may result in strong fluctuations of either field, while such quantities as the solid fraction or granular temperature will remain virtually constant. It is known that granular aggregates exhibit rigidity phase transition near the critical volume fraction $\nu_c$ [11]. When the volume fraction is near or above $\nu_c$, the granular material has elastoplastic rheology and below this critical value it behaves as a fluid. Near and above the critical volume fraction for the same boundary conditions the granular aggregate may exhibit either slow creeping flow, solid-like behavior, or both. The latter case, known as stick-slip phenomenon, is observed both experimentally and numerically [2,11,28]. In an experiment under constant volume boundary conditions, a series of stick-slip events occur without a significant change in the solid fraction, which is insensitive to global rearrangements relieving the accumulated stress. We expect the order parameter to be able to reflect such rearrangements and ultimately describe the corresponding phase transition.

### B. Stress tensor

The full stress tensor (30) consists of a contact (virial) part and the Reynolds part. In turn, the contact stress tensor can be split into the “solid contact” component $\sigma^s$ and the “fluid contact” component $\sigma^f$ in the same fashion as was done with contacts themselves. Combining the “fluid contact” component with the Reynolds stress, we obtain the full stress tensor as a sum of two parts

$$\sigma = \sigma^f + \sigma^s,$$

$$\sigma^s_{a\beta} = \frac{1}{2} \sum_c r^c_{a\beta} F^c,$$

$$\sigma^f_{a\beta} = \sigma^f_{a\beta} + \sigma^R_{a\beta} = \frac{1}{2} \sum_c r^c_{a\beta} F^c + \langle m \tilde{v}_a \tilde{v}_\beta \rangle,$$

where summation in $\Sigma'$ and $\Sigma''$ is restricted to “solid” and “fluid” contacts, respectively.

The “fluid” part of the stress tensor is due to short-term collisional stresses and the Reynolds stresses, whereas the solid part accounts for persistent force chains. The Reynolds contribution to the stress is negligibly small in the vicinity of the phase transition, but comes into play when the granular aggregate is highly fluidized. In the system, which is neither completely rigid nor completely fluidized we expect the coexistence (in time and space) of both phases. A particular grain may have both types of contacts at the same time, thus contributing to both $\sigma^f$ and $\sigma^s$. This picture is reminiscent of the concept of bimodal character of stress transmission in static contact network introduced by Radjai et al. [29,30].

**FIG. 1.** (Color online) Sketch of the granular shear flow model.

**V. TESTBED SYSTEM: COUETTE FLOW IN A THIN GRANULAR LAYER**

### A. Bifurcation diagram

We studied the fluidization transition in a thin (50×10) granular layer between two “rough plates” under fixed pressure $P$ and zero gravity conditions (Fig. 1). The parameters of simulations were $\mu_c = 0.5$, $e = 0.92$, $\Delta_c = 0.2$, $k_n = 2 \times 10^5$, $k_c/k_n = 1/3$, $\gamma_s = 16.7$. We used the same material parameters of grains throughout this section. The rough plates were simulated by two straight chains of large grains (twice as large as an average particle diameter) glued together. The layer was chosen narrow enough, so the properties of the granular layer (shear rate, shear stress components, order parameter, etc.) in the absence of gravity were approximately constant across the layer within 10% accuracy. Two opposite forces $\mathbf{F}_1 = -\mathbf{F}_2$ were applied to the plates along the horizontal $x$ axis to induce shear stress in the bulk. We started with weak forces not sufficient to initiate a shear flow and slowly ramped them up in small increments well above the critical yield force at which the granular flow started. After that we ramped the shear forces down until the granular layer was jammed again. At every “stop” we measured all stress components, strain rate, and the order parameter, and averaged the data over the whole layer and over time of each step. Figure 2 shows the strain rate $\dot{\gamma}$ (we drop subscripts $yx$ and $xy$)
at the strain rate) and the order parameter \( \rho \) as functions of the shear stress \( \sigma_{yx} \), which is approximated by the applied force \( F \) normalized by the layer length \( L_x \), for \( P = 40 \). As it is to be expected, the strain rate remains 0, and the order parameter is one until the shear stress reaches a certain critical value \( \sigma_1 \approx 12.6 \). This value differs slightly for different runs because of the finite system size and absence of self-averaging in the static regime. Above the yield stress, the strain rate abruptly jumps to a finite value \( \sim 0.15 \). At larger \( |\sigma_{yx}| \), the strain rate increases faster than it does linearly, and the order parameter rapidly approaches 0. The return curve corresponding to the diminishing of the shear stress follows roughly the same path, and then continues to another (smaller) value of the shear stress \( (\sigma_2 \approx 9.4) \). At this value the layer jams, the strain rate returns to 0, and the order parameter jumps back to 1.

The most striking feature of this figure is the hysteretic behavior of both the strain rate and the order parameter as a function of the shear stress. This hysteresis was anticipated in our order-parameter model [18,19]; however, now we are in a position to fit the model equations quantitatively. We repeated these simulations at several different values of the compressing pressure \( P \). Data for different pressure values in the flow regime fall onto the same universal curve if one normalizes the shear stress by the pressure (see Fig. 3). Assuming that there is an (unobserved) unstable branch of the bifurcation diagram, which merges with the stable branch at \( \delta \approx 0.26 \), we can make a simple analytic fit of this curve as

\[
F(\rho, \delta) = (1 - \rho)\left(\rho^2 - 2\rho_0 \rho + \rho_0^2 \exp[-A(\delta^2 - \delta_0^2)]\right) = 0 
\]

with \( \rho_0 = 0.6, A = 25, \delta_0 = 0.26 \) (see Fig. 3, line) and use it in the polynomial expansion of the free energy density which enters the order parameter equation (20):

\[
\mathcal{F}(\rho) = \int_0^\rho F(\rho, \delta) d\rho. 
\]

We also measured the density and the granular temperature of the grains as we decreased the shear force. These measurements could only be performed in the range \( \rho < 0.55 \) since for larger \( \rho \) the partially fluidized state is unstable. Note that the density of grains stays almost constant in a wide range of the order parameter \( \rho > 0.1 \) [see Fig. 4(a)].

The granular temperature (which is defined as \( T = \langle \vec{u}_i \vec{u}_i \rangle / 2 \)) normalized by the applied pressure \( P \) appears to be a unique function of the order parameter [Fig. 4(b)].

**B. Relaxation dynamics of the order parameter**

We probed the relaxation dynamics of the order parameter by performing the following numerical experiment. The granular layer was prepared as in the preceding section. Lateral shear forces were increased adiabatically until the granular system reached a metastable solid (jammed) state within a hysteretic region. Then the layer was perturbed by applying random forces to a small randomly selected fraction of particles. The dynamics of the order parameter varies depending on the magnitude of the perturbation. Figure 5 shows an example of the evolution from the same jammed state for two different magnitudes of initial perturbation. Interestingly, the relaxation back to the jammed state is very fast, whereas the relaxation toward stable shear flow is much slower. We believe that it has to do with inertia of grains and the upper plate, so the intrinsic time scale of the order parameter relaxation is rather small, \( O(1) \).

Unfortunately, our thin Couette flow system does not allow us to probe the local coupling of the order parameter
since the order parameter is uniformly distributed throughout the system. In the absence of this data, this coupling was modeled by the linear diffusion term in Eq. (20) with the constant diffusion coefficient. As we will see in the following section, this approximation indeed provides a good description for spatially nonuniform near-surface flow; however, the value of the diffusion coefficient appears to be a function of local stress.

### C. Fitting the constitutive relation

The next step is to fit the constitutive relation from MD simulations. To this end, we use the same Couette flow simulations, but now we analyze the “fluid stress” \( \sigma_{\alpha\beta}^f \) and the “static stress” \( \sigma_{\alpha\beta}^s \) separately during our ramp-down simulations at three different values of \( P \). Figure 6 shows a sample of these data for \( P = 30 \). At large \( \delta = F/(L_x P) \), when the order parameter \( \rho \) is low, the total stress is dominated by the fluid component, but as the flow stops and \( \rho \) approaches unity, the fluid stress turns to 0, and the total stress is equal to the static stress. Plotting \( \sigma_{\alpha\beta}^f/\sigma_{\alpha\beta}^s \) as a function of the order parameter \( \rho \) for different \( P \) [Figure 7(a)], we observe that all data collapse onto a single curve, which is well fitted by \( q(\rho) = (1 - \rho)^{2.5} \). The lines in Fig. 6 show the fit of the fluid and static stress tensors using Eqs. (15) and (16) with \( q(\rho) = (1 - \rho)^{2.5} \).

The fluid as well as solid parts of the stress tensor are nearly symmetric, \( \sigma_{yx}^f = \sigma_{xy}^f \), so the ratio \( \sigma_{yx}^f/\sigma_{xy}^s \) is described by the same scaling function \( q(\rho) \). On the other hand, the same procedure for the diagonal elements of the stress tensor yields a noticeably different scaling [see Fig. 7(b)]. Furthermore, a small but noticeable difference is evident between \( \sigma_{xx}^f/\sigma_{xx}^s \) and \( \sigma_{yy}^f/\sigma_{yy}^s \). More detailed analysis shows that, in fact, fluid parts of the diagonal components of the stress tensor \( \sigma_{xx}^f \) and \( \sigma_{yy}^f \) are nearly identical, and the difference is due to the solid part of the normal stresses (see Fig. 8). This observation is consistent with the fact that the diagonal terms of the static stress tensor are determined by the details of the external loading. On the other hand, in a completely fluidized state the diagonal terms are all equal to the hydrodynamic pressure \( p_f \) [31]. In a partially fluidized regime, the diagonal terms of the shear stress can be expressed as

\[
\sigma_{xx} = p_f / q_x(\rho), \quad \sigma_{yy} = p_f / q_y(\rho).
\]  

### Figure 5

(Color online) Relaxation of the order parameter towards shear flow (solid line) and jammed state (dashed line) for two different initial perturbations in a thin Couette system of 500 particles with \( P = 40 \), \( \sigma_{yy} = -12 \).

### Figure 6

(Color online) Fluid and static components of the shear stress in a thin granular layer (10×50) at external pressure \( P = 30 \) as a function of normalized external shear stress \( \delta = F/(L_x P) \): direct calculation (points), obtained from total stress using relations Eqs. (15) and (16) with \( q(\rho) = (1 - \rho)^{2.5} \) (lines).

### Figure 7

(Color online) Ratios of the fluid stress components to the corresponding full stress components \( \sigma_{\alpha\beta}^f/\sigma_{\alpha\beta} \) vs \( \rho \) for three different pressures \( P \): (a) shear stress components, closed symbols \( \sigma_{xx} \), open symbols \( \sigma_{yy} \), line is a fit \( q_x(\rho) = (1 - \rho)^{2.5} \); (b) normal stress components, closed symbols \( \sigma_{xx} \), open symbols \( \sigma_{yy} \), lines are the fits \( q_x(\rho) = (1 - \rho)^{3.9}, q_y(\rho) = (1 - \rho^{1.2})^{1.9} \).
Both functions $q_{x,y}(<p>)$ should approach 1 as $p \rightarrow 0$ (the normal stresses should be equal in the fluid state), but they may have different functional form to reflect the anisotropy of the static stress tensor. In our simple Couette flow, the diagonal stress tensor components can be well fitted by $q_{x}(p)=(1-p)^{1.9}$ and $q_{y}(p)=(1-p^{1.2})^{1.9}$ [see Fig. 7(b)]. So we observe that even in a partially fluidized regime, the “fluid phase” component indeed behaves as a real fluid with a well-behaved “partial” pressure $p_f$, which is zero in a solid state at $p=1$ and is becoming the full pressure in a completely fluidized state $p=0$.

Plotting the fluid shear stress versus the strain rate, we can test the validity of the Newtonian model for the stress-strain relation (14). Figure 9 shows $-\sigma_{y}^{f}$ vs $\dot{\gamma}$ for three different pressures $P = 20, 30, 40$. At small $\dot{\gamma}$ all three lines are close to the same straight line $\sigma_{y}^{f} = 12\dot{\gamma}$, which indicates that the Newtonian scaling for fluid shear stress holds reasonably well. The deviations at large $\dot{\gamma}$ are evidently caused by variations of temperature and density in the dilute regime. Note that in contrast, the full shear stress does not goes to 0 as $\dot{\gamma} \rightarrow 0$ [see Fig. 9(b)], so a viscosity coefficient conventionally defined as the ratio of the full shear stress to the strain rate diverges at the fluidization threshold as observed in Ref. [3].

Combining the Newtonian law for the fluid stress-strain dependence with the order parameter scaling of the fluid stress tensor, we arrive at the relationship between the full stress tensor and the strain rate tensor (19) with $\mu_f=12$, $q_x(p)=(1-p)^{1.9}$, $q_y(p)=(1-p^{1.2})^{1.9}$, $q(p)=(1-p)^{2.5}$.

**D. Toward dilute granular flows—granular temperature revisited**

While the above fittings have been made for the regime of a slow dense flow with $\nu \rightarrow \nu_c$, it is tempting to generalize the theoretical model so that it smoothly crosses over to the standard kinetic continuum theory (1)–(10) for $p \rightarrow 0$. This goal can be achieved by including the equation of state (6) and the equation for the granular temperature (3) back into the theory. The important difference with respect to the standard kinetic theory is that the pressure, which we calculate with Eq. (6), is not the total pressure, but the partial pressure associated with the fluid part of the stress tensor. Of course, as $p \rightarrow 0$, the static part of the stress tensor disappears, and the partial pressure becomes the total pressure.

We can test the relevance of this combined approach by calculating the spatial correlation function $G(\nu) = (1+\nu)^{-1}[\pi d^2 p_f/4\nu T - 1]$ with the values of fluid pressure $p_f$, temperature $T$ and density $\nu$ calculated in our testbed Couette flow at different external pressures $P$ and comparing it with the theoretical functions $G_{CFS}(\nu), G_{CFS}(\nu), G_{CL}(\nu)$ [Eqs. (11)–(13)]. Figure 10 shows that the Carnahan-Sterling formula works very well in the dilute range $\nu<0.67$ as expected. In the high density regime $G(\nu)$ approaches the free volume result (12), and the overall dependence is in agreement with the global interpolation $G_{CL}(\nu)$ by Luding [24].
the presented data strongly suggest that the constitutive relations for the fluid part of the stress tensor are well described by the standard granular hydrodynamics.

### E. Order parameter description of partially fluidized granular flows—take 2

Let us summarize the equations of the continuum theory as specified on the basis of the 2D molecular dynamics simulation of the thin Couette flow.

The mass, momentum, and energy conservation conditions are expressed by Eqs. (1)–(3). The order parameter equation now has the form

$$\frac{D \rho}{Dt} = D \nabla^2 \rho - (\rho - 1) \{ \rho^2 - 2 \rho \rho_f + \rho_f^2 \exp[-A (\delta^2 - \delta_f^2)] \}$$

with $\rho_f = 0.6$, $\delta_f = 0.26$, $A = 25$. As mentioned before, for the lack of simulation data, we assume linear diffusion coupling of the order parameter with a constant nondimensional diffusion coefficient $D$. The constitutive relation now reads

$$\sigma_{\alpha\beta} = [p_f q_{\alpha}(\rho) + (\mu_f - \lambda_f \text{Tr} \gamma' q(\rho)) \delta_{\alpha\beta} - \mu_f \gamma_{\alpha\beta} / q(\rho)]$$

with $q_{\alpha}(\rho) = (1 - \rho)^{1/9}$, $q_\gamma(\rho) = (1 - \rho^{1/3})^{1/9}$, $q(\rho) = (1 - \rho)^{2.5}$.

The equation of state and expressions for viscosity, thermal conductivity, and the energy dissipation have the same functional form as Eqs. (6)–(10), but they are now written for the “fluid” parameters $p_f$, $\mu_f$, $\lambda_f$, and $\varepsilon$.

### VI. SURFACE-DRIVEN SHEAR GRANULAR FLOW UNDER GRAVITY

In this section we apply the theoretical description that was formulated in the preceding section on the basis of numerical simulations of a thin Couette flow with no gravity to another model problem. We consider shear granular flow in a thick granular layer under gravity driven by the upper plate, which is pulled in a horizontal direction, see Fig. 12. A similar system has been studied experimentally by Nasuno et al. [2], as well as by Tsai et al. [7].

We simulated up to 20,000 particles in a rectangular box under a heavy plate, which was moved either with a constant speed $V_z$, or a constant force $F_z$. Periodic boundary conditions were assumed in a horizontal direction. After a transient, a quasistationary fluidization and shear flow established in the near-surface layer, while near the bottom grains remained in a nearly static jammed regime. Here, we show the results of several different runs with small (large) pressure and small (large) shear. The details of these runs are given in Table I. The vertical profiles of the density, flow velocity, and the order parameter are shown in Fig. 13. The density of grains remains nearly constant, very close to the maximum random packing density value, except for a narrow near-surface boundary layer. The most significant density variations were observed for the case $P10V50$ corresponding to a light, fast moving upper plate. The horizontal
velocity decays roughly exponentially off the plate in agreement with experimental evidence \[2,7\]. The vertical profiles of the order parameter demonstrate a well-defined transition from fluid state near the upper plate to solid state below. The width of the “interface” grows with the applied pressure \(P\), which indicates the stress dependence of the diffusion coefficient for the order parameter. Surprisingly, we found that the order parameter does not approach 1 at large depths, but instead seems to saturate at some value slightly below 1. We believe that this behavior is inherent to our 2D geometry with periodic boundary conditions on side walls. The moving upper plate oscillates vertically and produces vibrations in the bulk of granular layer. These slowly decaying with depth vibrations break weak contacts between particles that are not strongly pressed against each other (e.g., lying under

![Image](image_url)

**FIG. 12.** (Color online) The geometry of the MD simulation of a surface-driven shear flow.

<table>
<thead>
<tr>
<th>Run ID</th>
<th>(N_p)</th>
<th>(L_x)</th>
<th>(L_y)</th>
<th>(P)</th>
<th>(V_x)</th>
<th>(F_x/(PL_x))</th>
<th>(-\sigma_{yz})</th>
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<tr>
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<td>5 \times 10^3</td>
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<td>100</td>
<td>5</td>
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</tr>
<tr>
<td>(P10V50)</td>
<td>5 \times 10^3</td>
<td>50</td>
<td>100</td>
<td>50</td>
<td>5</td>
<td>6.0</td>
<td>6.0</td>
</tr>
<tr>
<td>(P50V5)</td>
<td>5 \times 10^3</td>
<td>50</td>
<td>100</td>
<td>5</td>
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<td>17.0</td>
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</tr>
<tr>
<td>(P50V50)</td>
<td>5 \times 10^3</td>
<td>50</td>
<td>100</td>
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<td>50</td>
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<tr>
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<tr>
<td>(P20F20XL)</td>
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<td>200</td>
<td>20</td>
<td>20.0</td>
<td>20.0</td>
<td>20.0</td>
</tr>
</tbody>
</table>

**TABLE I.** Parameter values for the simulations of deep Couette flows for different geometries and boundary conditions. The first six runs were performed at constant velocity of the top plate and the last two runs were for a constant horizontal force applied to the plate; for all runs \(\mu_s=0.3\), \(e=0.82\), \(\Delta_x=0.2\), \(k_n=2 \times 10^5\), \(k_l/k_n=1/3\), \(\gamma_n=16.7\).

FIG. 13. (Color online) Density (a), horizontal velocity (b), temperature (c), and the order parameter (d) profiles in a deep granular layer driven by upper moving plate for four different runs from Table I.

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We believe that in full 3D simulations with more realistic boundary conditions this effect may be less pronounced. In principle, it may be included in the theoretical description by proper averaging of fluctuations of the strain tensor in the spirit of Savage \cite{Savage16}. By averaging velocity fluctuations and forces acting on individual particles, we calculated vertical profiles of the fluid and solid parts of the shear and normal stress components \( \sigma_{\alpha\beta} \) (see Sec. IV). These profiles for run P10V50 are shown in Fig. 14. Strong fluctuations of the horizontal component of the stress tensor \( \sigma_{\alpha\beta} \) are mostly related to the static component of the tensor. According to Eqs. (15) and (16), fluid and solid parts of the shear stress components should be related to the shear component of the full stress tensor which in this geometry is roughly independent of \( y \) via the function \( q(r) \). Figure 15(a) depicts this function as a parametric plot of \( \sigma'_{yx}(y)/\sigma_{yx} \) vs \( \rho(y) \) made by using vertical profiles of stresses and the order parameter. As seen from this figure, the same fit \( q(\rho) = (1 - \rho)^{2.5} \) in (a), and \( q_1(\rho) = (1 - \rho^{1.2})^{1.9} \) in (b).

The dependence of the fluid part of the shear stress component on the strain rate (Fig. 16) shows the same behavior as for the thin Couette system: at small \( \dot{\gamma} \) the viscosity is nearly constant \( \mu_f \approx 12 \), and at larger \( \dot{\gamma} \) shear thinning is observed. Interestingly, the dependence of the local Reynolds shear stress on the local strain rate is well described by the Bagnold scaling \( \sigma'_{yx} \approx \dot{\gamma}^2 \). Eventually, at large \( \dot{\gamma} \), this scal-
ing should dominate the full stress-strain rate relationship. Figure 17 compares the behavior of the viscosity coefficient $\mu = \sigma_{yx} / \dot{\gamma}$ and $\mu_f = \sigma'_{yx} / \dot{\gamma}$ calculated along the vertical profiles of $\sigma$ and $\dot{\gamma}$, as a function of density $\nu$ and order parameter $\rho$. While the former diverges as $\nu \rightarrow \nu_c$ and $\rho \rightarrow 1$, the latter approaches the constant value $\mu_f \sim 12$, in agreement with the results of Sec. V.

As in the preceding section, we can extract the particle-particle correlation function by calculating $G(\nu) = (1 + e)^{-1} [\pi d^2 p_f / 4 \nu T - 1]$ using the vertical profiles of $\sigma_{yx}, T$, and $\nu$. Again, we obtain a good agreement with theoretical predictions based on the kinetic theory for fluid component of the stress tensor (Fig. 18).

Finally, we can compare the stationary vertical profiles of the order parameter and the horizontal velocity with theoretical predictions. In most of our numerical simulations we specified the velocity of the upper plate rather than the applied force. That allowed us to study the regimes of slow dense flows, which would be unstable had we applied a constant shear force. The shear stress tensor component $\sigma_{yx}$ in the stationary regime was indeed constant across the layer [see, for example, Fig. 14(c)]. However, due to slippage near the moving plate the relation between the plate speed and the shear stress is complicated. We do not address the issue of boundary conditions here as it is a subject of a separate study (see for example, Ref. [32]). Here we simply use the values that are obtained in numerical simulations (the last column in Table I), as parameters in our theoretical model.

In the stationary regime, the relevant stress tensor components are specified as follows:

\begin{equation}
\end{equation}

FIG. 16. (Color online) “Fluid” shear stress vs local shear strain rate for several runs: (a) total fluid shear stress, (b) Reynolds part of the shear stress.

FIG. 17. (Color online) Full viscosity $-\sigma_{yx} / \dot{\gamma}$ (solid symbols) and “fluid” viscosity $-\sigma'_{yx} / \dot{\gamma}$ (open symbols) coefficients as functions of density (a) and the order parameter (b) for two runs.

FIG. 18. (Color online) Particle-particle correlation function as a function of density for several runs of the thick Couette flow simulations.
$\sigma_{yy} = P + (H - y)$, \hfill (39)

$\sigma_{yx} = \sigma_{xy} = \text{const}$, \hfill (40)

where $P$ is the external pressure applied to the upper wall, and $H$ is the thickness of the granular layer (note that it is different from $L$, due to compaction). In the regime of slow dense flow, the volume fraction of grains is nearly constant, close to the random close packing density, and so the flow can be assumed incompressible.

We also need to specify the boundary conditions for the order parameter at the top and bottom plates. This is a serious issue in its own right, which we will address elsewhere. Here we simply impose no-flux boundary conditions both at the top and the bottom plate for the order parameter, $\partial_y \rho(0) = \partial_y \rho(H) = 0$.

We limit ourselves with the case of slow dense flow regime, when the granular temperature plays a minor role, and the granular flow can be considered incompressible. This allows us to use the reduced set of Eqs. (2), (37) and (38) with the fixed viscosity $\mu_f = 12$. The stationary shear flow solution of the continuum equations can be found numerically as follows. Since the components of the full stress tensor are assumed known, we solve the time-dependent order parameter equation (37) using the pseudospectral method until the solution reaches a stationary state. The resulting solution for the order parameter is then used to obtain the velocity profile by integrating the constitutive relation (38) from the bottom ($y = 0$) up. Since the grains are strongly compressed near the rough bottom plate due to gravity, we assume the no-slip boundary condition for the horizontal velocity at $y = 0$. The momentum conservation equation (2) is satisfied automatically. Thus, obtained profiles of velocity and the order parameter were compared with our 2D molecular dynamics simulations.

The results of the comparison between the velocity and order parameter profiles obtained in simulation and by using
the continuum theory are shown in Fig. 19 for four runs P10V5 (a), P10V50 (b), P50V5 (c), P50V50 (d). The only fitting parameter used was the diffusion constant D in the order parameter equation, which has not been determined in our testbed analysis. We used \( D = 1 \) for runs P10V5 and P10V50, \( D = 5 \) for P50V5 and \( D = 10 \) for P50V50. From this we can conclude that the diffusion coefficient depends on the local stress tensor; however, more elaborate numerical experiments are needed to pinpoint this dependence more quantitatively. All other parameters were identical for all four cases as specified in Sec. V E. The vertical profiles of the order parameter and the horizontal velocities are reasonably well described by the theory. However, for low pressure runs P10V5 and P10V50, the horizontal velocity profiles deviate from the numerical data presumably because the viscosity coefficient is no longer a constant in a dilute region near the top plate.

VII. CONCLUSIONS

In this paper we performed a series of numerical simulations of 2D wall-driven granular flows. These simulations were designed with a specific goal, to quantify the continuum theory of partially fluidized granular flows, which was introduced ad hoc earlier [18,19]. We defined the order parameter as a ratio of the number of static contacts to the total coordination number averaged over a small mesoscopic volume. Using simulations of a thin Couette flow between two rough plates, we determined the free energy density for the order parameter. Simulations confirmed that the ratio of the shear to the normal stress in the bulk of the granular flow can parametrize the stationary states of the order parameter equation. The same simulations allowed us to determine the detailed structure of the constitutive relation. We split the total stress tensor into the fluid and solid components, in which the former comprises the Reynolds stresses and the stresses transmitted through short-term collisions, while the latter is formed by the force chains through persistent contacts. The ratio of fluid and solid stress components is indeed determined by the order parameter through scaling functions \( q(\rho), q_{r,s}(\rho) \). Remarkably, the fluid component of the stress tensor is a linear function of the strain rate \( \dot{\gamma} \) in the slow dense flow regime. This justifies the Newtonian scaling of the stress-strain relationship adopted in the theory.

Using the calibrated theory, we studied the flow structure of a thick surface driven Couette granular flow under gravity. We found the theoretical predictions to be in a good quantitative agreement with simulations.

The evidence presented here suggests an intriguing interpretation for the order parameter description of dense and slow granular flows. The granular material under shear stress appears to be similar to a multiphase system with the fluid phase “immersed” into the solid phase. The fluid phase behaves as a simple Newtonian fluid for small shear rates when the density is almost constant, but exhibits shear thinning at larger shear rates when the density begins to drop. We observed that the Reynolds part of the fluid shear stress obeys the Bagnold scaling \( \sigma_{rr}^R \sim \gamma^2 \). We anticipate that for very large shear rates when the Reynolds stress becomes dominant, the overall stress tensor should exhibit Bagnold scaling locally.

While this theory is primarily intended for dense and slow granular flows, we have shown that it can be combined with existing models of rapid granular flows based on the kinetic theory of granular gases. This requires to drop the assumption of incompressibility and include the equation for the granular temperature. Our simulations showed that the kinetic theory works well for the fluid part of the stress tensor in the whole range of densities from dilute regime to the critical random close packing density.

Many issues still remain open. The spatially nonuniform dynamics of the order parameter requires a more detailed study. We found that the diffusion constant postulated in Eq. (37) appears to be a function of the normal shear stress as well as the local strain rate; however, we do not have sufficient numerical data to provide a quantitative description of this dependence. It would be of interest to analyze the propagation of a fluidization front in a granular layer prepared in a meta-stable static regime. Such simulations could provide an insight into the mechanisms of the local coupling of the order parameter.

The molecular dynamics algorithm employed is based on a number of approximations. These approximations, however well tested and widely accepted [8–10], directly affect the results of our fitting the continuum model. For example, if one replaces the Hookian model of particle interaction with a Hertzian one, an appreciable difference in the structure of the order parameter may be observed. More numerical work is needed to quantify the relationships between the microscopic parameters of the system (nature of collisions, restitution coefficient, friction, etc.) and the parameters of the continuum model.

Finally, our simulations were limited by 2D systems, and of course the resulting continuum theory can only be directly applicable to 2D systems. While we anticipate the structure of the model to remain in 3D systems, the specific form of the fitting functions should change. This future work will allow us to perform a comparison of the 3D model not only with numerical simulations but also with experimental data.

ACKNOWLEDGMENTS

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[23] In L.E. Silbert, D. Ertas, G.S. Grest, T.C. Halsey, and D. Levine, Phys. Rev. E 65, 051307 (2002), a similar quantity, a fraction of sliding contacts averaged over the whole flow region, was introduced. For a chute flow, it exhibited a first-order transition as a function of the chute angle.
[25] This assumption implies that stress tensors $\sigma$, $\sigma'$, $\sigma''$ are collinear, which as we see in the following sections, is a reasonable assumption for our 2D simulations, however, does not have to hold in all cases. In those circumstances, the order parameter $\rho$ would become a tensor itself.
[31] In fact, in highly dilute regimes at large shear rates, the normal components of the stress tensor also show anisotropy [e.g., O.R. Walton and R.L. Braun, J. Rheol. 30, 949 (1986); I. Goldhirsh and N. Sela, Phys. Rev. E 54, 4458 (1996)]; however, for the slow flows we are concerned with here, this effect can be neglected.